

ABSTRACT OF THE DISCLOSURE

A projectile retrieval system includes a screw drive for moving bullets and bullet fragments to move bullets from a bullet deceleration area to a remote location without the need for a person to handle the bullets. Preferably, the screw drive is configured so that there is no need to stop use of the bullet deceleration area while the screw drive is transporting the bullets. In a preferred embodiment, a vacuum system is also connected to a transport housing about the screw drive to move lead dust away from the bullet deceleration area.